6ES7510-1DK03-0AB0





SIMATIC DP, CPU 1510SP-1 PN for ET 200SP, central processing unit with work memory 200 KB for program and 1 MB for data, 1st interface: PROFINET IRT with 3-port switch, 6 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2 SIMATIC DP, CPU 1510SP F-1 PN for ET 200SP, central processing unit with 300 KB work memory for program and 1 MB for data, 1st interface: PROFINET IRT with 3-port switch, 6 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2 SIMATIC DP, CPU 1512SP-1 PN for ET 200SP, central(*)

General information			
Product type designation	CPU 1510SP-1 PN		
HW functional status	FS04		
Firmware version	V4.0		
 FW update possible 	Yes		
Product function			
 I&M data 	Yes; I&M0 to I&M3		
 Module swapping during operation (hot swapping) 	Yes; Multi-hot swapping		
 Isochronous mode 	Yes; only with PROFINET; with minimum OB 6x cycle of 500 µs		
SysLog	Yes		
Engineering with			
STEP 7 TIA Portal configurable/integrated from version	V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0		
Configuration control			
via dataset	Yes		
Control elements			
Mode selector switch	1		
Supply voltage			
Rated value (DC)	24 V		
permissible range, lower limit (DC)	19.2 V		
permissible range, upper limit (DC)	28.8 V		
Reverse polarity protection	Yes		
Mains buffering			
 Mains/voltage failure stored energy time 	10 ms		
Input current			
Current consumption (rated value)	0.48 A		
Current consumption, max.	0.7 A		
Inrush current, max.	1.34 A; Rated value		
l²t	0.3 A ² ·s		
Power			
Infeed power to the backplane bus	8.05 W		
Power loss			
Power loss, typ.	3.5 W		
Memory			
Number of slots for SIMATIC memory card	1		
SIMATIC memory card required	Yes		
Work memory			
integrated (for program)	200 kbyte		
• integrated (for data)	1 Mbyte		
Load memory			

Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	6 ns
for word operations, typ.	7 ns
for fixed point arithmetic, typ.	9 ns
for floating point arithmetic, typ.	37 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1
0:	59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	0 05 505
Number range Size may	0 65 535
Size, max. FC	200 kbyte
Number range	0 65 535
• Size, max.	200 kbyte
OB	200 100/10
• Size, max.	200 kbyte
Number of free cycle OBs	100
Number of time alarm OBs	20
Number of delay alarm OBs	20
Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 250 μs
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	1
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of skintap OBs Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 216 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
 Retentivity adjustable 	Yes

Retentivity preset	No
Local data	INC
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	04 kbyte, max. To kb per block
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	2 040, max. number of modules / submodules
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All imputs are in the process image
per integrated IO subsystem	32 kbyte, All outputs are in the process image
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	o kbyte
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	0 hDyto
Number of subprocess images, max.	32
Address space per module	- J2
Address space per module, max.	288 byte; For input and output data respectively
Address space per module, max. Address space per station	200 byte; I of hiput and output data respectively
Address space per station, max.	2 560 byte; for central inputs and outputs; depending on configuration; 2 048
* Address space per station, max.	bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
• integrated	1
• Via CM	0
Rack	
Modules per rack, max.	82; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
 Quantity of operable ET 200SP modules, max. 	64
 Quantity of operable ET 200AL modules, max. 	16
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
• Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• on DP, device	Yes; Via CM DP module
• in AS, master	Yes
• in AS, device	Yes
on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1; Via CM DP module
Optical interface	Yes; Via SIMATIC BusAdapter
1. Interface	
Interface types	
RJ 45 (Ethernet)	Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Number of ports	3; 1. integr. + 2. via BusAdapter
integrated switch	Yes
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BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 Of which IO devices with IRT, max. 	64
 Number of connectable IO Devices for RT, max. 	128
— of which in line, max.	128
 Number of IO Devices that can be simultaneously activated/deactivated, max. 	8; in total across all interfaces
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
— PROFINET Security Class	1
Update time for IRT	
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 μs of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
— With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s 3 875 μ s)
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— Isochronous mode	No
— IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes
 Number of IO Controllers with shared device, max. 	4
 activation/deactivation of I-devices 	Yes; per user program
 Asset management record 	Yes; per user program
— PROFINET Security Class	SNMP Configuration and DCP Read Only
2. Interface	
Interface types	
• RS 485	Yes; Via CM DP module
Number of ports	1
Protocols	
PROFIBUS DP master	Yes
PROFIBUS DP device	Yes
SIMATIC communication	Yes

 Number of connections, max. 	48; Of which 4 each reserved for ES and HMI
 max. number of DP devices 	125; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Services	PROFIBOS OF PROFINET
	No
Equidistance Isochronous mode	No
activation/deactivation of DP devices	Yes
Interface types	165
RJ 45 (Ethernet)	Yes
• 100 Mbps	Yes
Autoropoing	Yes
 Autocrossing Industrial Ethernet status LED 	Yes
RS 485	165
Transmission rate, max.	12 Mbit/s
Protocols	12 WIDIUS
PROFIsafe	No
	No
Number of connections • Number of connections, max.	128: via integrated interfaces of the CDLL and connected CDs / CMs
 Number of connections, max. Number of connections reserved for ES/HMI/web 	128; via integrated interfaces of the CPU and connected CPs / CMs 10
Number of connections via integrated interfaces	88
 Number of connections via integrated interfaces Number of connections per CP/CM 	32
•	32 16
Number of S7 routing paths Redundancy mode	10
·	Yes
H-Sync forwarding Media redundancy	165
Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager;
— MIN	MRP Client
 MRP interconnection, supported 	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
 Switchover time on line break, typ. 	200 ms; For MRP, bumpless for MRPD
 Number of stations in the ring, max. 	50
SIMATIC communication	
 PG/OP communication 	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
Data record routing	Yes
 S7 communication, as server 	Yes
 S7 communication, as client 	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
 several passive connections per port, supported 	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; max. 78 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
• Encryption	Yes; Optional
Web server	V 01 1 1 1
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	50
— Number of sessions, max.	50
 number of simultaneous HTTP calls, max. 	4

— HTTP request body, max.	131 072 byte	
OPC UA	101 012 byte	
Runtime license required	Yes; "Small" license required	
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call	
 Application authentication 	Yes	
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256	
— User authentication	"anonymous" or by user name & password	
 Number of connections, max. 	4	
 Number of nodes of the client interfaces, recommended max. 	1 000	
 Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_I max. 	300	
 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20	
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100	
 Number of simultaneous calls of the client instructions for session management, per connection, max. 	1	
 Number of simultaneous calls of the client instructions for data access, per connection, max. 	5	
 Number of registerable nodes, max. 	5 000	
 Number of registerable method calls of OPC_UA_MethodCall, max. 	100	
 Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20	
OPC UA Server	Yes; data access (read, write, subscribe), method call, alarms & condition (A&C), custom address space, role-based access control	
 Application authentication 	Yes	
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss	
 User authentication 	"anonymous" or by user name & password	
 — GDS support (certificate management) 	Yes	
Number of sessions, max.	32	
 Number of accessible variables, max. 	50 000	
 Number of registerable nodes, max. 	10 000	
 Number of subscriptions per session, max. 	50	
— Sampling interval, min.	100 ms	
— Publishing interval, min.	200 ms	
 Number of server methods, max. 	20; max. 20 concurrently running jobs each for asynchronous instructions OPC_UA_ServerMethodPre and OPC_UA_ServerMethodPost	
 Number of inputs/outputs per server method, max. 	20	
 Number of monitored items, recommended max. 	4 000; for 1 s sampling interval and 1 s send interval	
Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"	
 Number of nodes for user-defined server interfaces, max. 	15 000	
Alarms and Conditions	Yes	
— Number of program alarms	100	
Number of alarms for system diagnostics	50	
Further protocols	V. MORRIGITOR	
• MODBUS	Yes; MODBUS TCP	
S7 message functions		
Number of login stations for message functions, max.	32	
number of subscriptions, max.	250	
number of tags/attributes for subscriptions, max.	2 000	
Program alarms	Yes	
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH	
Number of loadable program messages in RUN, max.	5 000	
Number of simultaneously active program alarms		
Number of program alarms	600	
Number of alarms for system diagnostics	100	
 Number of alarms for motion technology objects 	160	

Test commissioning functions			
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems		
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)		
Single step	Yes		
Number of breakpoints	8		
Profiling	Yes		
Status/control			
Status/control variable	Yes		
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters		
Number of variables, max.	inputorouputo, memory bito, BBS, distributed 1703, timero, counters		
of which status variables, max.	200; per job		
of which control variables, max.	200; per job		
Forcing	200, μει job		
Forcing	Yes		
Forcing, variables	Peripheral inputs/outputs		
Number of variables, max.	200		
Diagnostic buffer	200		
<u> </u>	Yes		
Number of entries may	1 000		
Number of entries, max. of which powerful proof.	500		
— of which powerfail-proof	000		
Traces	4		
Number of configurable Traces Moment cite por trace, max	4 512 khuto		
Memory size per trace, max. Intervente/diagnostics/status information.	512 kbyte		
Interrupts/diagnostics/status information			
Diagnostics indication LED			
• RUN/STOP LED	Yes		
• ERROR LED	Yes		
MAINT LED	Yes		
Monitoring of the supply voltage (PWR-LED)	Yes		
 Connection display LINK TX/RX 	Yes		
· •			
Supported technology objects			
· •	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool		
Supported technology objects Motion Control	program; selection guide via the TIA Selection Tool		
Supported technology objects			
Supported technology objects Motion Control • Number of available Motion Control resources for	program; selection guide via the TIA Selection Tool		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects	program; selection guide via the TIA Selection Tool		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	program; selection guide via the TIA Selection Tool 1 120		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	program; selection guide via the TIA Selection Tool 1 120 40		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	program; selection guide via the TIA Selection Tool 1 120 40 80		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	program; selection guide via the TIA Selection Tool 1 120 40 80 160		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value)	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources Per speed-controlled axis Per positioning axis Per synchronous axis Per external encoder Per output cam Per cam track Per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Controller	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization		
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Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint environmental product declaration	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Astep PID_Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint environmental product declaration Global warming potential, (total) [CO2 eq] global warming potential, (during production) [CO2	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint environmental product declaration Global warming potential, (total) [CO2 eq]	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes 83.2 kg		

global warming potential, (after end of life cycle)				
COZ early Product Number PROFINET Security President Pre	eq]	0.040 lim		
Secure Book 1		-0.949 kg		
Special firmware update	product functions / security / header			
Security Report Security	PROFINET Security Class	1		
Ambient conditions	signed firmware update	Yes		
Ambient conditions Ambient temperature during operation • horizontal installation, min. • horizontal installation, min. • vertical installation, max. • or 'C' • vertical installation, max. • or 'C' • installation attitude above sea level, max. • for 'C	Secure Boot	Yes		
Ambient temperature during operation	safely removing data	Yes		
	Ambient conditions			
	Ambient temperature during operation			
• vertical installation, min.	 horizontal installation, min. 	-30 °C; No condensation		
	 horizontal installation, max. 	60 °C		
Altitude during operation relating to sea level	 vertical installation, min. 			
• Installation altitude above sea level, max. 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual		50 °C		
configuration / programming / header Programming language Yes — LAD Yes — FBD Yes — STL Yes — SCL Yes — CFC Yes — CFC Yes — CRAPH Yes • Copy protection Yes • Copy protection Yes • Block protection Yes • Protection for confidential configuration data Yes • Protection level: Read/write protection Yes • Protection level: With protection Yes • Protection level: Read/write protection Yes • Protection level: With protection Yes • Protection level: Complete protection				
Configuration / programming / header		5 000 m; Restrictions for installa	ation altitudes > 2 000 m,	see manual
Programming language				
FBD		.,		
- CFC				
Section Sect				
User program protection				
● User program protection/password protection Copy protection Elock protection Protection level: Write protection Protection level: W		res		
• Copy protection • Block protection • Block protection • Protection of confidential configuration data • Protection of confidential configuration data • Protection level: Write protection • Protection level: Write protection • Protection level: Pead/write protection • Protection level: Pead/write protection • Protection level: Complete protection • User administration • Ves; device-wide and centralized • Number of groups • Number of groups • Number of protes • Number of protes • Number of roles • Number of groups • Number of roles • Number of roles • Number of roles • Number of roles • Number of groups • Number of roles • Number of groups • Number of roles • Number of groups • Number of groups • Number of roles • Number of groups	·	Vec		
Access protection Yes Access protection • protection of confidential configuration data • protection level: Write protection Yes • Protection level: Read/write protection Yes • Protection level: Write protection for Fallsafe No • Protection level: Complete protection Yes • Protection level: Complete protection Yes • Number of users 100 • Number of groups 100 • Number of groups 50 • Number of roles 50 programming / cycle time monitoring / header • lower limit • lower limit adjustable minimum cycle time • upper limit adjustable maximum cycle time • User and protection level: Complete protection 100 mm • Height 117 mm Depth 75 mm Weights Version Classification • Class 14 27-24-26-07 • Class 9 27-24-26-07 • Class 9 27-24-26-07 • Class 9 27-24-26-07				
Access protection				
		103		
Protection level: Write protection Protection level: Read/write protection Protection level: Read/write protection Protection level: Write protection		Yes		
Protection level: Read/write protection Protection level: Write protection for Failsafe Protection level: Write protection for Failsafe Protection level: Complete protection Ves Protection level: Complete protection Ves User administration Ves; device-wide and centralized Number of groups Number of groups Number of roles Number of roles Number of roles Protection level: Write protection Number of groups Number of groups Number of roles Number o				
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● User administration ● Number of users ● Number of groups ● Number of proles ● Number of roles ● Ower limit ● upper limit ● upper limit ● upper limit ● upper limit ■ 117 mm Depth 75 mm Weights Weight, approx. Classifications Classification	Protection level: Write protection for Failsafe	No		
 Number of users Number of groups Number of roles N	Protection level: Complete protection	Yes		
● Number of groups ● Number of roles 50 programming / cycle time monitoring / header ● lower limit adjustable minimum cycle time ● upper limit adjustable maximum cycle time Dimensions Width 100 mm Height 1117 mm Depth 75 mm Weights Weight, approx. 265 g Classifications Version Classification ● Class 14 27-24-26-07 eClass 9.1 27-24-26-07 eClass 9 27-24-26-07 eClass 8 27-24-26-07 eClass 9 12 27-24-26-07 eClass 8 27-24-26-07 eClass 8 27-24-26-07 eClass 8 27-24-26-07 eClass 8 27-24-26-07 eClass 6 27-24-26-07 eClass 7 eCla	User administration	Yes; device-wide and centralize	ed	
● Number of roles 50 programming / cycle time monitoring / header ● lower limit adjustable minimum cycle time adjustable maximum cycle time ● upper limit adjustable maximum cycle time Dimensions Width 100 mm Height 1117 mm Depth 75 mm Weights Weight, approx. 265 g Classifications Version Classification	Number of users	100		
programming / cycle time monitoring / header	Number of groups			
● lower limit ● upper limit ● upper limit ● upper limit Adjustable maximum cycle time adjustable maximum cycle time Dimensions Width 100 mm Height 117 mm Depth 75 mm Weights Weight, approx. Classifications Version Classification	 Number of roles 	50		
● upper limit adjustable maximum cycle time Dimensions	programming / cycle time monitoring / header			
Dimensions Width 100 mm Height 117 mm Depth 75 mm Weight, approx. Classification Classification eClass 14 27-24-26-07 eClass 12 27-24-26-07 eClass 9.1 27-24-26-07 eClass 9 27-24-26-07 eClass 8 27-24-26-07 eClass 8 27-24-26-07 eClass 7.1 27-24-26-07 eClass 6 27-24-26-07	 lower limit 	adjustable minimum cycle time		
Width 100 mm Height 117 mm Depth 75 mm Weights Weight, approx. 265 g Classifications Classification eClass 14 27-24-26-07 eClass 12 27-24-26-07 eClass 9.1 27-24-26-07 eClass 9 27-24-26-07 eClass 8 27-24-26-07 eClass 7.1 27-24-26-07 eClass 6 27-24-26-07	• upper limit	adjustable maximum cycle time		
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Weight, approx. Classifications Version Classification eClass 14 27-24-26-07 eClass 12 27-24-26-07 eClass 9.1 27-24-26-07 eClass 9 27-24-26-07 eClass 8 27-24-26-07 eClass 7.1 27-24-26-07 eClass 6 27-24-26-07 eClass 6 27-24-26-07 eClass ETIM 9 EC001603	·	75 mm		
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ETIM 9 EC001603		eClass	7.1	27-24-26-07
		eClass	6	27-24-26-07
FTIM 8 EC001603		ETIM	9	EC001603
LTIW C EC001003		ETIM	8	EC001603

ETIM	7	EC001603
IDEA	4	3565
UNSPSC	15	32-15-17-05

Approvals / Certificates

General Product Approval

Manufacturer Declara-<u>tion</u>







Miscellaneous



General Product Approval

For use in hazardous locations

<u>KC</u>





<u>FM</u>

CCC-Ex



For use in hazardous locations

Marine / Shipping



Miscellaneous

CCC-Ex







Marine / Shipping

NK / Nippon Kaiji Kyokai





CCS (China Classification Society)



other

Profibus

other

Environment

PROFINET



last modified:

12/8/2024

