## **Data sheet**



Figure similar

SIMATIC ET 200SP Open Controller, CPU 1515SP PC2 + HMI 2048PT, 8 GB RAM (basic device 6ES7677-2DB40-0AA0), 128 GB CFast with Windows 10 IoT Enterprise LTSC 2019 64-bit, S7-1500 Software Controller CPU 1505SP V2x and WinCC Runtime Advanced V17 preinstalled, with 2048 PowerTags license; interfaces: 1x slot CFast, 1x slot SD/MMC, 1x connection for ET 200SP BusAdapter PROFINET, 1x 10/100/1000 Mbps Ethernet, 2x USB 3.0, 2x USB 2.0, 1x DisplayPort; documentation on CFast,

General information	
Product type designation	CPU 1515SP PC2
HW functional status	from FS04
Firmware version	V20.8
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated from version</li> </ul>	V16
Installed software	
<ul> <li>Visualization</li> </ul>	WinCC Runtime Advanced V16
<ul> <li>Control</li> </ul>	S7-1500 Software Controller CPU 1505SP
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	5 ms
Input current	
Current consumption (rated value)	1.8 A; Full processor load, incl. ET 200SP modules and using USB
Current consumption (in no-load operation), typ.	0.5 A
Current consumption, max.	2.9 A
l²t	0.426 A²-s; with starting current inrush
Power	
Active power input, max.	43 W; incl. ET 200SP modules and using USB
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	16 W
Processor	
Processor type	Intel Atom E3940, 1.6 GHz, 4 cores
Memory	
Type of memory	DDR3L
Main memory	8 GB RAM
CFast memory card	Yes; 128 GB flash memory
SIMATIC memory card required	No
Work memory	
• integrated (for program)	1 Mbyte

<ul> <li>integrated (for data)</li> <li>integrated (for CPU function library of CPU Runtime)</li> <li>Load memory</li> <li>integrated (on PC mass storage)</li> <li>Backup</li> <li>with UPS</li> <li>with non-volatile memory</li> <li>Yes; all memory areas declared retentive</li> <li>with non-volatile memory</li> <li>CPU-blocks</li> <li>Number of elements (total)</li> <li>6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements</li> </ul>	
Load memory	
<ul> <li>integrated (on PC mass storage)</li> <li>Backup</li> <li>with UPS</li> <li>with non-volatile memory</li> <li>Yes; all memory areas declared retentive</li> <li>Yes</li> <li>CPU-blocks</li> <li>Number of elements (total)</li> <li>6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements</li> </ul>	
Backup         ● with UPS       Yes; all memory areas declared retentive         ● with non-volatile memory       Yes         CPU-blocks         Number of elements (total)       6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements	
<ul> <li>with UPS         <ul> <li>with non-volatile memory</li> </ul> </li> <li>Yes; all memory areas declared retentive</li> <li>Yes</li> <li>CPU-blocks</li> <li>Number of elements (total)</li> <li>6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements</li> </ul>	
<ul> <li>with non-volatile memory</li> <li>CPU-blocks</li> <li>Number of elements (total)</li> <li>6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements</li> </ul>	
CPU-blocks  Number of elements (total)  6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements	
Number of elements (total)  6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements	
constants, etc. are also regarded as elements	
DB	
Number, max.     5 999; Number range: 1 to 65535	
• Size, max. 5 Mbyte	
FB	
• Number, max. 5 998; Number range: 1 to 65535	
• Size, max. 1 024 kbyte	
FC	
Number, max.     5 999; Number range: 1 to 65535	
• Size, max. 1 024 kbyte	
OB	
Size, max.     1 024 kbyte	
Number of free cycle OBs	
Number of time alarm OBs     20	
Number of delay alarm OBs     20	
Number of cyclic interrupt OBs     20	
Number of process alarm OBs     50	
Number of DPV1 alarm OBs	
Number of isochronous mode OBs	
Number of technology synchronous alarm OBs     2	
Number of startup OBs     100	
Number of asynchronous error OBs	
Number of synchronous error OBs     2	
Number of diagnostic alarm OBs	
Nesting depth	
• per priority class 24	
Counters, timers and their retentivity	
S7 counter	
• Number 2 048	
Retentivity	
— adjustable Yes	
IEC counter	
Number     Any (only limited by the main memory)	
Retentivity	
— adjustable Yes	
S7 times	
• Number 2 048	
Retentivity	
— adjustable Yes	
IEC timer	
Number     Any (only limited by the main memory)	
Retentivity	
— adjustable Yes	
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max. 410 kbyte; For storage in NVRAM; for storage in mass storage 5 242 02	) bytes
Flag	
• Size, max. 16 kbyte	
Number of clock memories     8; 8 clock memory bit, grouped into one clock memory byte	
Data blocks	
Retentivity adjustable     Yes	
Retentivity preset	
Local data	

<ul> <li>per priority class, max.</li> </ul>	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192
I/O address area	0.102
• Inputs	32 kbyte; All inputs are in the process image
• Outputs	32 kbyte; All outputs are in the process image
Subprocess images	
Number of subprocess images, max.	32
Hardware configuration	
Integrated power supply	Yes
Number of distributed IO systems	20
Number of DP masters	
• Via CM	1
Number of IO Controllers	
• via PC interfaces	1
Rack	
<ul> <li>Modules per rack, max.</li> </ul>	64; CPU 1515SP PC + 64 modules + server module
<ul> <li>Quantity of operable ET 200SP modules, max.</li> </ul>	64
<ul> <li>Quantity of operable ET 200AL modules, max.</li> </ul>	16
<ul> <li>Number of lines, max.</li> </ul>	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	01013
Clock	
• Type	Hardware clock
Hardware clock (real-time)	Yes; Resolution: 1 s
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.  Cleak a make a principle.	10 s; Typ.: 2 s
Clock synchronization	Voc
• supported	Yes
• to DP, master	Yes
on Ethernet via NTP	Yes
• on Windows clock, device	Yes
Interfaces	
Number of industrial Ethernet interfaces	2
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1
Number of RS 485 interfaces	1; Via CM DP module
Number of USB interfaces	4; 2x USB 2.0, 2x USB 3.0 on front side
Number of SD card slots	1
Video interfaces	
Graphics interface	1x DisplayPort
1. Interface	
Interface type	PROFINET
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Number of connections	88
Interface types	
• RJ 45 (Ethernet)	Yes; Via BusAdapter BA 2x RJ45
— Transmission rate, max.	100 Mbit/s
<ul> <li>Industrial Ethernet status LED</li> </ul>	Yes
<ul> <li>Number of ports</li> </ul>	2
• integrated switch	Yes
BusAdapter (PROFINET)	Yes; Compatible BusAdapter: BA 2x RJ45, BA 2x FC, BA 2x SCRJ (from FS03, V2.2), BA SCRJ / RJ45 (from FS03, V3.1), BA SCRJ / FC (from FS03, V3.1), BA 2x LC (from FS03, V3.3), BA LC / RJ45 (from FS03, V3.3), BA LC / FC (from FS03, V3.3)
Protocols	
PROFINET IO Controller	Yes
PROFINET IO Device	Yes

SIMATIC communication	Vac
SIMATIC communication     Open IF communication	Yes
Open IE communication	Yes
Web server	Yes
PROFINET IO Controller	
Services	W.
— Isochronous mode	Yes
— shortest clock pulse	500 μs
— IRT	Yes
— PROFlenergy	Yes
— Prioritized startup	Yes; max. 32 PROFINET devices; if you want to use the "Prioritized startup" functionality in STEP 7 for the PROFINET interface of the CPU, the CPU and the device must be separated by means of a switch (e.g. SCALANCE X205)
<ul> <li>Number of connectable IO Devices, max.</li> </ul>	128
<ul> <li>Of which IO devices with IRT, max.</li> </ul>	64
— of which in line, max.	64
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	128
— of which in line, max.	128
<ul> <li>Number of IO Devices that can be simultaneously</li> </ul>	8
activated/deactivated, max.  — IO Devices changing during operation (partner	Yes
ports), supported	
Number of IO Devices per tool, max.	
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 μs: 625 μs 3 875 μs)
Update time for RT	minimum cycle time start from 500 µs
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
PROFINET IO Device	- · · · · · · · · · · · · · · · · · · ·
Services	
— Isochronous mode	No
— shortest clock pulse	500 μs
— IRT	Yes
— PROFlenergy	Yes
Prioritized startup	Yes
— Shared device	Yes
Number of IO Controllers with shared device, max.	4
Number of 10 Controllers with shared device, max.      Asset management record	Yes
2. Interface	
	Integrated Ethernet interface
Interface type automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autorossing	Yes
Interface types	160
• •	Vec. Integrated
RJ 45 (Ethernet)  Transmission rate, max	Yes; Integrated
— Transmission rate, max.	1 000 Mbit/s
— Industrial Ethernet status LED	No 4
Number of ports	1
3. Interface	PROFINIA W AMAR
Interface type	PROFIBUS with CM DP
Number of connections	44

late of a control of	
Interface types	V
• RS 485	Yes
Protocols	
PROFIBUS DP master	Yes
PROFIBUS DP device	Yes
SIMATIC communication	Yes
PROFIBUS DP master	
max. number of DP devices	125
Services	
— Equidistance	No
— Isochronous mode	No
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
Interface types	
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
<ul> <li>Number of connections, max.</li> </ul>	88
<ul> <li>Number of connections reserved for ES/HMI/web</li> </ul>	10
Number of S7 routing paths	16
Redundancy mode	
Media redundancy	
— MRP	Yes
— MRPD	Yes
<ul> <li>Switchover time on line break, typ.</li> </ul>	200 ms
Number of stations in the ring, max.	50
SIMATIC communication	
<ul> <li>PG/OP communication</li> </ul>	Yes
<ul> <li>S7 routing</li> </ul>	Yes
<ul> <li>S7 communication, as server</li> </ul>	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
User data per job, max.	64 kbyte; BSEND/BRCV: 64 KB; PUT/GET: 960 bytes
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 048 byte
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Via Windows and PROFINET interface
• HTTPS	Yes; Via Windows and PROFINET interface
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; From SW CPU 1505SP V2.6
OPC UA Server	Yes; Data access (read, write, subscribe), runtime license required
<ul> <li>Application authentication</li> </ul>	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— Security policies	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	Yes; "anonymous" or by user name & password
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32

Program alarms	Yes
Number of configurable program messages, max.	10 000
Number of simultaneously active program alarms	1 000
Number of program alarms	1 000
Number of alarms for system diagnostics	200
Number of alarms for motion technology objects	160
Test commissioning functions	Vac Darellal online access possible for up to 0 anning systems
Joint commission (Team Engineering)  Status block	Yes; Parallel online access possible for up to 8 engineering systems Yes; up to 8 simultaneously
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
Variables	Inputs, outputs, memory bits, DB, times, counters
Number of variables, max.	,,,,,
— of which status variables, max.	200
— of which control variables, max.	200
Forcing	
• Forcing	Yes
Forcing, variables	Inputs, outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
<ul> <li>Number of entries, max.</li> </ul>	1 000
<ul><li>of which powerfail-proof</li></ul>	300
Traces	
<ul> <li>Number of configurable Traces</li> </ul>	4
<ul> <li>Memory size per trace, max.</li> </ul>	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
Supported technology objects	
Motion Control	Yes
<ul> <li>Number of available Motion Control resources for technology objects</li> </ul>	2 400
<ul> <li>Required Motion Control resources</li> </ul>	
— per speed-controlled axis	40; per axis
— per positioning axis	80; per axis
— per synchronous axis	160; per axis
— per external encoder	160; per axis 80; per external encoder
— per external encoder  — per output cam	160; per axis 80; per external encoder 20; per cam
<ul><li>per external encoder</li><li>per output cam</li><li>per cam track</li></ul>	160; per axis 80; per external encoder 20; per cam 160; per cam track
<ul><li>per external encoder</li><li>per output cam</li><li>per cam track</li><li>per probe</li></ul>	160; per axis 80; per external encoder 20; per cam
<ul> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle</li> </ul>	160; per axis 80; per external encoder 20; per cam 160; per cam track
<ul> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle</li> </ul>	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
<ul> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> </ul>	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_3Step	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_3Step  • PID-Temp	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_3Step  • PID-Temp  Counting and measuring	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
per external encoder per output cam per cam track per probe  • Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_3Step • PID-Temp  Counting and measuring • High-speed counter	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_3Step  • PID-Temp  Counting and measuring  • High-speed counter  Standards, approvals, certificates	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
— per external encoder  — per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_3Step  • PID-Temp  Counting and measuring  • High-speed counter  Standards, approvals, certificates  CE mark	160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  Yes

RCM (formerly C-TICK)	Yes		
Ambient conditions	7.00		
Ambient temperature during operation			
	-20 °C		
<ul><li>min.</li><li>max.</li></ul>	Up to 60 °C with max. 32 ET 20 200SP modules	00SP modules; up to 55 °C	C with max. 64 ET
<ul> <li>horizontal installation, min.</li> </ul>	-20 °C		
<ul> <li>horizontal installation, max.</li> </ul>	60 °C		
• vertical installation, min.	-20 °C		
vertical installation, max.	50 °C; With max. 32 ET 200SP	modules	
Ambient temperature during storage/transportation	55 S, THE HEAL SE ET 2555.	, incuality	
• min.	-40 °C		
• max.	70 °C		
Vibrations	10 0		
Operation, tested according to IEC 60068-2-6	Yes		
Transport, tested acc. to IEC 60068-2-6	Yes		
Shock testing	165		
-	Yes		
tested according to IEC 60068-2-6     tested according to IEC 60068-3-37			
tested according to IEC 60068-2-27     tested according to IEC 60068-3-30	Yes		
• tested according to IEC 60068-2-29	Yes		
Storage/transport, tested acc. to IEC 60068-2-27	Yes		
Operating systems			
pre-installed operating system	Windows 10 IoT Enterprise 201	16 LTSB, 64bit, MUI	
configuration / header			
configuration / programming / header			
Programming language			
— LAD	Yes		
— FBD	Yes		
— STL	Yes		
— SCL	Yes		
— CFC	No		
— GRAPH	Yes		
Know-how protection			
User program protection/password protection	Yes		
Copy protection	Yes		
Block protection	Yes		
Access protection	1 00		
Protection level: Write protection	Yes		
Protection level: Read/write protection	Yes		
Protection level: Read/write protection     Protection level: Complete protection	Yes		
	res		
programming / cycle time monitoring / header			
• lower limit	adjustable minimum cycle time		
• upper limit	adjustable maximum cycle time	<b>)</b>	
Open Development interfaces			
Size of ODK SO file, max.	5.8 Mbyte		
Peripherals/Options			
SD card	Optionally for additional mass s	storage	
Dimensions			
Width	160 mm		
Height	117 mm		
Depth	75 mm		
Weights			
Weight, approx.	0.83 kg		
Classifications			
		Version	Classification
		Ve151011	Giassilication
	eClass	14	27-24-26-07
	eClass eClass	14 12	27-24-26-07 27-24-26-07
	eClass	12	27-24-26-07

eClass	8	27-24-26-07
eClass	7.1	27-24-26-07
eClass	6	27-24-26-07
ETIM	9	EC001603
ETIM	8	EC001603
ETIM	7	EC001603
IDEA	4	3565
UNSPSC	15	32-15-17-05

Approvals / Certificates

**General Product Approval** 

Marine / Shipping

Manufacturer Declaration





Miscellaneous





Environment



last modified: 12/8/2024 🖸