



L7C Servo Drive & Motor Xmotion



Beyond technology, the revolution of Industry 4.0!

Achieve automation innovation with LSIS L7C Servo Drive

Compact size considering productivity improvement and system efficiency, various built-in functions, complete the innovation of automation at a competitive price.



L7C Servo Drive



Control power/Main power

- Unification of power for integrated power board
- 0.1 ~ 1kW Drive line-up for support



Optimal system implementation/competitive cost ratio

- Unused FPGA due to optimization



Maintain compatibility

- Compatibility with existing



Maintain and improve

- Maintain current control cycle [5kHz]
- Added operation mode(indirect memory/1MB, L7P specific)



power unification
egrated control board and
single phase AC220V

mentation with
ization of MCU usage

L7S I/O pin map

L7S specification
ycle (10kHz), speed/position
exing mode) and improved
ation)



Specification (L7C Servo Drive)

Item	L7CA001U	L7CA002U	L7CA004U	L7CA008U	L7CA010U	
Input power	Single phase AC200 ~ 230[V] (-15~+10%), 50~60[Hz]					
Rated current[A]	1.4	1.7	3.0	5.2	6.75	
Peak current[A]	4.2	5.1	9.0	15.6	20.25	
Encoder type	Quadrature (Incremental), Biss-B, Biss-C (Absolute, Incremental)					
Control performance	Speed control range	Maximum 1:5000				
	Frequency response	Maximum 1[KHz] or above (When using 19Bit Serial Encoder)				
	Speed variation ratio	$\pm 0.01 [\%]$ or lower [when load changes between 0 and 100%] $\pm 0.1 [\%]$ or lower [temperature $25 \pm 10^\circ\text{C}$]				
	Accel/Decel time	Straight or S-curve acceleration/deceleration [0-10,000[ms], possible to be set by one[ms] unit]				
	Input frequency	1[Mpps], line driver / 200[kpps], open collector				
	Input pulse type	Symbol + Pulse series, CW+CCW, A/B Phase				
RS-422	Specification	ANSI/TIA/EIA-422 standard specifications				
	Protocol	MODBUS-RTU				
	Synchro method	Asynchronous				
	Power consumption	100[mA]				
	Transmission speed	9,600/19,200/38,400/57,600bps				
	Distance	Maximum 200[m]				
	Terminating resistance	Connecting the outside connector (CN1 7Pin, 28Pin connection), Built-in 120Ω				
Digital In/Output	Digital input	Input voltage range : DC12V ~ DC24V Total 10 input channels (allocable) Total 34 function's input can be used selectively for assignment. (*SV_ON, *SPD/LVFS1, *SPD2/LVFS2, *SPD3, *A-RST, *JDIR, *POT, *NOT, *EMG, *STOP, START, REGT, HOME, HSTART, ISEL0, ISEL1, ISEL2, ISEL3, ISEL4, ISEL5, PCON, GAIN2, P_CL, N_CL, MODE, PAUSE, ABSRQ, JSTART, PCLR, AOV, INHIBIT, EGEAR1, EGEAR2, ABS_RESET) * Basic allocation signal				
	Digital output	Service rating : DC24V $\pm 10\%$, 120mA 5 of 10 input channels are allocable, 3 channels are fixed with AL00, AL01, AL02 Total 19 function's input can be used selectively for assignment. (*ALARM, *READY, *ZSPD, *BREAK, *INPOS1, ORG, EOS, TGON, TLMT, VLMT, INSPD, WARN, INPOS2, IOUT0, IOUT1, IOUT2, IOUT3, IOUT4, IOUT5) * Basic allocation signal				
Analog Input		2 Channel Analog speed input (Command/Override) $\pm 10\%$ Analog torque input (Command/Limit) $\pm 10\%$				
USB communication	Function	Firmware download, parameter setting, tuning, secondary function, parameter copy				
	Connect	PC				
	Communication standard	USB 2.0 full speed (Applies standard)				
Internal function	Dynamic braking	Standard built-in brake (Activated when the servo alarm goes off or when the servo is off),				
	Regenerative braking	Both default built-in and external installation possible				
	Display function	7 segments (5DIGIT)				
	Additional function	Gain tuning, alarm history, JOG operation, origin search				
	Protection function	Excessive current/voltage/overload/overheating/speed, excessive current limit, low voltage, encoder/position following/current sensing fail				
Environment	Operating temperature / Storage temperature	0~50°C / -20 ~ 65°C				
	Operating humidity / Storage humidity	Below 80[%]RH / Below 90[%]RH(Avoid dew-condensation)				
	Environment	Indoor, avoid corrosive, inflammable gas or liquid, and electrically conductive dust.				

High resolution of magnetic sensing method Magnetic Absolute Serial Encoder



Magnetic Absolute Serial Encoder Built-in Motor



High speed serial communication

- Position data output by high-speed serial communication
- High compatibility maintenance by using the same communication method as existing products



High resolution position data output

- High resolution of magnetic sensing method
- Position data output of 17 bits (131,072 counts) per revolution
- Position data per revolution is always displayed in absolute position



High environmental protection

- High resistance to outside substances such as oil and dust
- High durability against external vibration and shock
- Motor shaft disk protection



Built-in auto gain tuning function

- Auto gain tuning in response to external environment
- Always keep optimal signal condition

Specification (Magnetic Absolute Serial Encoder Built-in Motor)

Servo motor (APM-□□□□YK)	FALR5A	FAL01A	FAL015A	FBL01A	FBL02A	FBL04A	FCL04A	FCL06A	FCL08A	FCL10A	FCL03D	FCL05D	FCL06D	FCL07D
Applicable Drive	L7□A001	L7□A002	L7□A001	L7□A002	L7□A004	L7□A008	L7□A010	L7□A004	L7□A008					
Flange size(□)	□40		□60						□80					
Rated output [kW]	0.05	0.1	0.15	0.1	0.2	0.4	0.4	0.6	0.75	1	0.3	0.45	0.55	0.65
Rated torque [N·m]	0.16	0.32	0.48	0.32	0.64	1.27	1.27	1.91	2.39	3.18	1.43	2.15	2.63	3.1
Rated torque [kgf·cm]	1.62	3.25	4.87	3.25	6.49	12.99	12.99	19.49	24.36	32.48	14.62	21.92	26.8	31.67
Max. instantaneous torque [N·m]	0.48	0.96	1.43	0.96	1.91	3.82	3.82	5.73	7.16	9.55	4.3	6.45	7.88	9.31
Max. instantaneous torque [kgf·cm]	4.87	9.74	14.62	9.74	19.48	38.96	38.98	58.47	73.08	97.44	43.85	65.77	80.39	95.01
Rated current [A]	0.95	1.25	1.73	0.95	1.45	2.6	2.58	3.81	5.02	5.85	2.5	3.05	3.06	3.83
Max. current [A]	2.85	3.75	5.28	2.85	4.35	7.8	7.75	11.42	15.07	17.5	7.51	9.16	9.18	11.5
Rated speed [r/min]					3,000							2,000		
Max. speed [r/min]					5,000							3,000		
Inertia [kg·m ² ×10 ⁻⁴]	0.023	0.042	0.063	0.091	0.147	0.248	0.53	0.897	1.264	1.632	0.53	0.897	1.264	1.63
Inertia [gfcms ²]	0.024	0.043	0.065	0.093	0.15	0.253	0.541	0.915	1.29	1.665	0.541	0.915	1.29	1.66
Allowable load inertia ratio	30 Times of Motor Inertia	20 Times of Motor Inertia							30 Times of Motor Inertia					
Rated power rate [kW/s]	10.55	23.78	35.34	11.09	27.6	27.07	30.6	40.66	45.09	62.08	38.73	51.47	54.56	59.03
Speed/Position detector	Standard						Serial single - Turn built - In type (17bit)							
Specifications & features	Structure						Fully closed self cooling IP67							
	Rated time						Continuous							
	Ambient temp						Operating: 0~40[°C] Storage: -10~60[°C]							
	Ambient humidity						90[%]RH below [Avoid dew-condensation]							
	Atmosphere						Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.							
Weight [kg]	0.31	0.45	0.61	0.56	0.74	1.06	1.52	2.14	2.68	3.3	1.26	2.12	2.66	2.78

* Brake is not applicable for FAL015A



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